

Matérn Gaussian Processes on Riemannian Manifolds

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Abstract

Gaussian processes are an effective model class for learning unknown functions, particularly in settings where accurately representing predictive uncertainty is of key importance. Motivated by applications in the physical sciences, the widely-used Matérn class of Gaussian processes has recently been generalized to model functions whose domains are Riemannian manifolds, by re-expressing said processes as solutions of stochastic partial differential equations. In this work, we propose techniques for computing the kernels of these processes on compact Riemannian manifolds via spectral theory of the Laplace-Beltrami operator, allowing them to be trained via standard scalable techniques such as inducing points. This enables Riemannian Matérn GPs to be used in mini-batch, online, and non-conjugate settings, and makes them more accessible to machine learning practitioners.

The Euclidean Matérn kernel

$$k(x,x') = \sigma^2 \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\sqrt{2\nu} \frac{\|x-x'\|}{\kappa}\right)^{\nu} K_{\nu} \left(\sqrt{2\nu} \frac{\|x-x'\|}{\kappa}\right)^{\nu}$$

 σ^2 : variance κ : length scale ν : smoothness $\nu \to \infty$: recovers squared exponential kernel

The Matérn kernel defines a Gaussian process $f : \mathbb{R}^d \to \mathbb{R}$.

A no-go theorem for kernels on manifolds

We'd like to define analogs of Matérn and squared exponential GPs $f: M \to \mathbb{R}$, where (M, q) is a Riemannian manifold.

Candidate generalization for $\nu \to \infty$ via geodesics

$$k_{\text{naïve}}(x, x') = \sigma^2 \exp\left(-\frac{d_g(x, x')^2}{2\kappa^2}\right)$$

Theorem. (Feragen et al. [2]) Let M be a complete Riemannian manifold without boundary. If $k_{\text{naïve}}$ is a positive semi-definite kernel for all κ , then M is isometric to a Euclidean space.

 \implies need a different candidate generalization



This gives a Karhunen—Loéve-type expansion, with $f_n(\cdot)$ analogous to Fourier features.

References

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- equation approach. JRSSB 73(4), 2011.

(c) Standard deviation

(d) One posterior sample